

# NOAA AVHRR DERIVED AEROSOL OPTICAL DEPTH (AOD): VALIDATION USING AERONET DATA IN AN ALPINE ENVIRONMENT

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**Abstract** - The aim of this study is the retrieval of aerosol optical depth from the National Oceanic and Atmospheric Administration (NOAA) Advanced Very High Resolution Radiometer (AVHRR) sensor over land. The region of interest covers central Europe ranging from 50°N to 40.5°N and from 0°E to 17°E including the European Alps. On the temporal scale, we limit the data set to afternoon NOAA-16 passes of the entire year 2002. In this region, there are sixteen stations from the Aerosol Robotic Network (AERONET) at which we can compare the ground-based versus the space borne measurements.

The aerosol optical depth retrievals from NOAA AVHRR are analysed in detail for the AERONET site Ispra (Italy). The temporal characteristics of the aerosol optical depth are well preserved, independent of the viewing geometry. However, there is an offset between the ground-based measurements and the satellite observations. The reason for this offset has to be further investigated. Improvements of the cloud masking are expected to decrease the amount of scatter. We can conclude that aerosol retrieval over land using AVHRR is a challenging task but it is possible to extract some valuable results.

**Keywords:** Aerosol Optical Depth, NOAA AVHRR

## 1. INTRODUCTION

Current state of the art space borne imaging radiometers like the Moderate Resolution Imaging Spectro-radiometer (MODIS) or the Multi-angle Imaging SpectroRadiometer (MISR) offer great possibilities for aerosol remote sensing. On the contrary, AVHRR offers a unique temporal coverage of over twenty years. The National Oceanic and Atmospheric Administration (NOAA) generates operational maps of the aerosol optical depth (AOD) over oceans [Stowe *et al.*, 1997]. Many remote sensing applications over land require AOD data, e.g. for atmospheric correction. The retrieval of AOD over land is more demanding because the surface reflectance is generally not only higher, so it provides less sensitivity to changes in aerosols, but varies spatially and temporally. Additionally, knowledge of the Bidirectional Reflectance Distribution Function (BRDF), which describes the angular reflectance properties, is required. Inaccuracies of 0.01 of the surface reflectance can result in AOD variations of  $\pm 0.1$  [Soufflet *et al.*, 1997].

The long term goal is to develop a procedure to estimate AOD from AVHRR suitable for real-time processing as well as for analyzing historic data. In this study we compare AOD data from AVHRR with ground-based measurements from AERONET.

## 2. DATA

The two data sources in this study are the NOAA AVHRR level1b data set, which has been pre-processed to provide cloud-free top of atmosphere (TOA) reflectance and aerosol optical depths from AERONET. Additionally, meteorological data (vertically integrated water vapor and sea level pressure at 12:00 UTC) from the Alpine Model (aLMo) produced by MeteoSwiss and total column ozone data (12:00 UTC) from the National Center for Environmental Prediction (NCEP) are used. In this study, we limit our data set to NOAA-16 afternoon passes of the entire year 2002.

### 2.1 AVHRR Data Set

The data presented in this paper uses observations from the 5-channel AVHRR on board the operational polar NOAA satellites. The instrument measures emitted and reflected radiance in the following bands: 0.58-0.68 (channel 1), 0.725-1.10 (channel 2), 3.55-3.93 (channel 3), 10.3-11.3 (channel 4) and 11.5-12.5 (channel 5) micrometers. The nominal instrument spatial resolution is approximately 1.1km. The NOAA AVHRR data are ingested by a receiving station located in Bern, Switzerland (46.917°N / 7.467°E). Since August 2001, we are in an operational status to receive and process all data covering the European Alps in near real-time. The data set in this paper consists of all NOAA-16 afternoon passes for the year 2002 and is mapped to a latitude-longitude grid, covering central Europe and the alpine region from 40.5°N to 50°N and 0°E to 17°E.

Pre-processing of NOAA-AVHRR level1b imagery for the retrieval of aerosol optical depth incorporates calibration of the visible channels 1 and 2 according to the NOAA KLM users guide [Goodrum *et al.*, 1999].

For improving the georeferencing, a feature matching algorithm is used to geocode the satellite imagery with sub-pixel accuracy. An orthorectification of the imagery is essential in an alpine region to overcome the displacement errors introduced by the topography. An automated procedure, which uses a terrain model based on the GTOPO30, was developed and implemented.

### 2.2 AERONET Data Set

The Aerosol Robotic Network (AERONET) is a world-wide federation of ground-based sun-sky radiometers. The network imposes standardization of instruments, calibration and processing. The data is centrally archived and available in three processing levels (unscreened (L1.0), cloud-screened (L1.5) and cloud-screened and quality-assured (L2.0)). According to Holben [Holben *et al.*, 1998], the accuracy is about  $\pm 0.02$ . For

the year 2002, there is data for 16 AERONET stations within our research area. To get a larger and consistent data set, only L1.5 data has been used because L2.0 data were only available for seven stations. To be able to compare the AERONET data with the AVHRR AOD retrievals, the AERONET data from different wavelengths are interpolated to 0.55 micrometers using a 2<sup>nd</sup>-order polynomial fit of the logarithmic wavelengths.

### 3. AEROSOL RETRIEVAL FROM NOAA-16 AVHRR

Classical approaches to retrieve aerosol optical depth (AOD) from NOAA AVHRR use surface targets with known reflectance characteristics. These targets consist mainly of water bodies and dark dense vegetation (DDV) [Kaufman and Sendra, 1988],[Soufflet *et al.*, 1997]. Our region of interest is located in the middle of Europe and densely populated; dark dense vegetation targets are sparse and not uniformly distributed. Lakes with a sufficient size are also few in numbers.

In general, surface reflectance over land in channel 1 is rather low and shows a significant deviation from an ideal lambertian surface. While for a lambertian surface the surface reflectance is independent from the satellite zenith angle and from forward or backward scattering, most natural surfaces have a more complex behavior which is expressed by the Bidirectional Reflectance Distribution Function (BRDF). There are many studies and models dealing with this problem, however, the application of a BRDF model requires accurate information about the surface type, which is often not available or outdated. To omit errors introduced by an inaccurate BRDF model we try to determine the BRDF from the data itself and follow partly the ideas of Knapp and Stowe [Knapp and Stowe, 2002]. For each cloud-free pixel a function of the top of atmosphere reflectance versus the satellite zenith angle can be plotted. We assume that the lowest reflectance values within a certain satellite zenith angle interval represent a nearly aerosol-free observation.

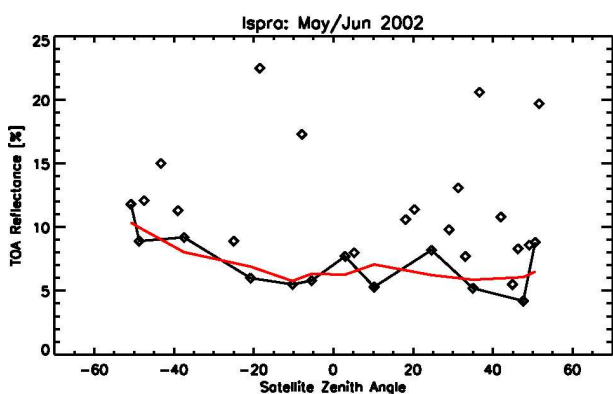


Figure 1. Top of atmosphere reflectance from NOAA-16 AVHRR for May/June 2002 (diamonds). The black line represents the top of atmosphere reflectance for aerosol-free conditions. It is the result from selecting the minimum reflectance within 10 degree intervals of the satellite zenith angle. The boxcar average (width of 3) is shown in red.

In this sense, the lowest reflectance values describe the reflectance deviations due to variations of the satellite zenith angle. To account for variations of the surface reflectance we split the data set into six two-month periods; this should at least minimize some seasonal variations of the surface reflectance. An example for the station of Ispra, Italy (45.80°N / 8.62°E) is shown in Figure 1.

The major advantage of this method is that it allows getting an estimate of the channel 1 reflectance for all surfaces independent of their land cover type. The cloud- and aerosol-free reflectance data is then atmospherically corrected and can be called cloud- and aerosol-free surface reflectance. The radiative transfer code used for the atmospheric correction of the top of atmosphere reflectance and for the retrieval of the aerosol optical depth is the updated SMAC [Rahman and Dedieu, 1994] algorithm. Updated means that it is no longer based on the 5S [Tanre *et al.*, 1990] code but on the newer version 6S [Vermote *et al.*, 1997]. Using SMAC, we can retrieve the aerosol optical depth using high resolution (7km × 7km) vertically integrated water vapor and surface pressure information as well as 1° × 1° ozone data for each pixel. A continental aerosol model [D'Almeida *et al.*, 1991] is expected to be most appropriate for this region.

### 4. RESULTS

To validate the AOD retrievals from NOAA-16 AVHRR, we can compare the retrievals to ground-based measurements taken at AERONET sites. In the following section we will discuss the results for the AERONET station of Ispra, Italy because this stations offers the largest amount of data for the year 2002.

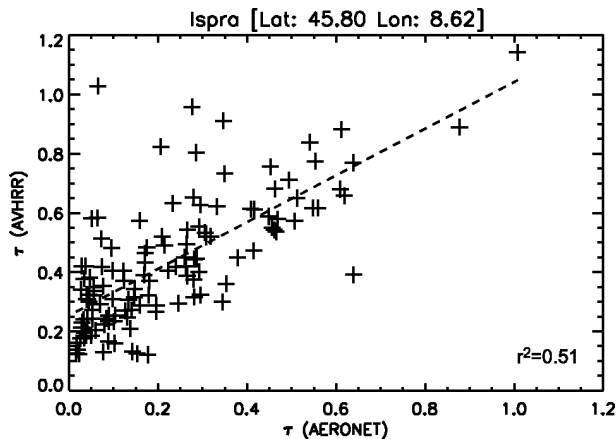


Figure 2. Aerosol optical depth retrieved from NOAA-16 AVHRR versus AERONET ground-based measurements for the year 2002 at Ispra, Italy. The maximum time difference between the two measurements is 45 minutes.

Figure 2 shows the scatter plot of the AVHRR results versus the AERONET data. Only data, which has been acquired within 45 minutes before or after the satellite pass, is

considered in this graph. Figure 2 shows a rather large amount of scatter, however a clear trend is visible ( $r^2=0.51$ ). Additionally, a clear lower boundary is visible, i.e. the AVHRR retrieved data generally overestimates the aerosol optical depth. A second, upper boundary is in contrary not visible, an indicator that the cloud masking was not always successful. The retrievals from AVHRR are able to reproduce the temporal variations of the aerosol optical depth (Figure 3).

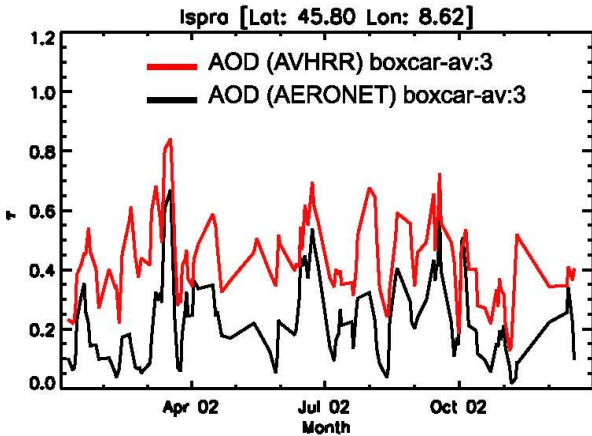


Figure 3: Time series of the aerosol optical depth from AERONET stations and retrieved from NOAA AVHRR.

Despite the clear offset, the AVHRR retrieval results perform well. High and low aerosol events are well represented and there is no seasonal trend. Additionally, the performance of the AOD retrieval with respect to the satellite zenith angle has been further examined (Figure 4).

This graph shows the retrieval error, i.e.  $\tau_{AVHRR} - \tau_{AERONET}$ , plotted versus the satellite zenith angle. The retrieval error shows basically no trend but is rather constant with a mean of about 0.2.

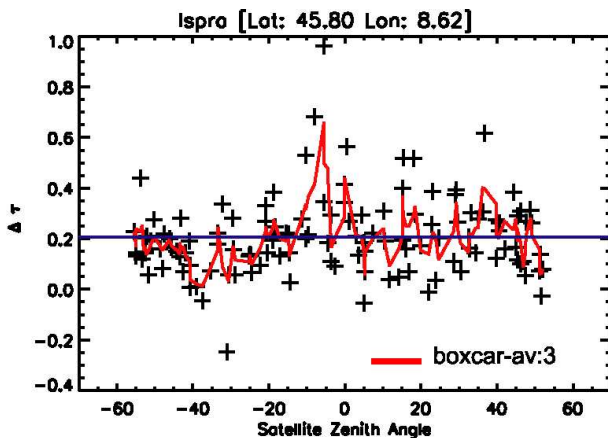


Figure 4. The retrieval error, i.e. the deviation of the AOD between the AERONET data and the AVHRR retrieval, plotted versus the satellite zenith angle.

## 5. DISCUSSION AND CONCLUSION

Figure 2–4 revealed some problems which have varying influence on the retrieval of AOD from AVHRR over heterogeneous land surfaces:

- Instrumental errors like sensor noise, calibration, etc. It is well known that the signal to noise ratio of the AVHRR sensor is rather low compared to the latest space borne imaging radiometers. Also the calibration is more difficult due to a missing in-flight calibration. Ignatov and Stowe [Ignatov and Stowe, 2002] reported a 20% decrease in aerosol optical depth over a sixteen month period over the ocean. This decrease is likely to be at least partly induced by a drift of the calibration. Using the pixel-wise BRDF corrected surface reflectance should reduce the influence of calibration uncertainties due to its limitation to two-month periods substantially.
- Retrieval uncertainties Retrieval uncertainties contain possible error sources during the retrieval. This includes inaccuracies of the description of the radiative transfer code, water vapor, ozone and pressure data as well as the selection of an appropriate aerosol model.
- Cloud masking Ignatov and Stowe [Ignatov and Stowe, 2002] state that "With little doubt, cloud screening is of comparable (if not greater) importance for accurate remote sensing than the aerosol retrieval algorithm itself." We can confirm this statement with our data.
- Surface reflectance The use of a pixel-wise BRDF corrected surface reflectance seems to be a feasible way to retrieve aerosol optical depth over land. Most former studies [Soufflet *et al.*, 1997] have been restricted to positive satellite zenith angles (forward scattering) to limit the effects of BRDF. This limitation is not necessary when using a pixel-wise BRDF corrected surface reflectance. Additionally, this method is not restricted to specific land cover types like the widely used AOD retrieval over dark dense vegetation targets. However, the procedure needs still some further adjustments. The pixel-wise BRDF corrected surface reflectance includes not only dark pixels like the dark dense vegetation method but instead the surface reflectance can exceed values of 10%. This affects the sensitivity to changes in aerosol adversely.

According to Holben [Holben *et al.*, 1998], the accuracy of AERONET measurements should be  $\pm 0.02$ . To compare AVHRR and AERONET results, the AERONET data has been interpolated to the same wavelength as the AOD from AVHRR. This might incorporate additional errors.

Totalling the results of this study, we can conclude that aerosol retrieval over land using AVHRR is a challenging task but it is possible to extract some valuable results. When incorporating a pixel-wise BRDF corrected surface reflectance, the covered area can be extended compared to classical approaches. Also,

restricting the AVHRR data set to specific view angles is obsolete. Direct comparison of AVHRR retrieved AOD versus AERONET data yields a large amount of scatter but generally a clear trend is visible. The temporal characteristics of the aerosol optical depth are well preserved, independent of the viewing geometry. However, there's still an offset between the ground-based measurements and the satellite observations. The reason for this offset might be a too low surface reflectance.

Due to the interaction with sensor noise, the selection of the minimum reflectance within certain intervals of the satellite zenith angle favours values, which have a too low surface reflectance. The noise level of the AVHRR sensor could therefore explain the offset between the AVHRR retrieved results and the measurements from AERONET. However, further investigations are necessary.

In the future, we hope to decrease scatter by refining the cloud masking scheme. This should possess the largest potential for a further improvement of the retrieval accuracy.

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